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**Garage**A self-hosted alternative to S3 for object storage



#### Deuxfleurs

A non-profit self-hosting collective, member of the CHATONS network



### Stable vs Resilient

#### Building a "stable" system:

Enterprise-grade systems typically employ:

- RAID
- Redundant power grid + UPS
- Redundant Internet connections
- Low-latency links
- **...**
- ightarrow costly, only worth at DC scale
- $\rightarrow$  still risk of DC-level incident...

#### Building a <u>resilient</u> system:

An alternative, cheaper way:

- Commodity hardware (e.g. old desktop PCs)
- Commodity Internet (e.g. FTTB, FTTH) and power grid
- Geographical redundancy (multi-site replication)

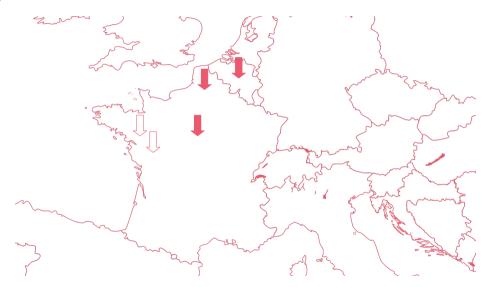
### Example: our infrastructure at Deuxfleurs



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## Object storage: simpler than file systems

Only two operations:

- ▶ Put an object at a key
- ► Retrieve an object from its key

(and a few others)

Sufficient for many applications!







## The data model of object storage

Object storage is basically a key-value store:

Key: file path + name	Value: file data + metadata
index.html	Content-Type: text/html; charset=utf-8
	Content-Length: 24929
	  dinary blob>
img/logo.svg	Content-Type: text/svg+xml
	Content-Length: 13429
	  dinary blob>
download/index.html	Content-Type: text/html; charset=utf-8
	Content-Length: 26563
	  dinary blob>

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### Implementation: consensus vs weak consistency

#### **Consensus-based systems:**

- **Leader-based:** a leader is elected to coordinate all reads and writes
- ► Allows for **sequential reasoning**: program as if running on a single machine
- Serializability is one of the strongest consistency guarantees
- **Costly**, the leader is a bottleneck: leader elections on failure take time

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#### Weakly consistent systems:

- ▶ Nodes are equivalent, any node can originate a read or write operation
- ► Operations must be independent, conflicts are resolved after the fact
- Strongest achievable consistency: read-after-write consistency (using quorums)
- ► Fast, no single bottleneck; works transparently with offline nodes

### Why avoid consensus?

Consensus can be implemented reasonably well in practice, so why avoid it?

- ► **Software complexity:** RAFT and PAXOS are complex beasts; harder to prove, harder to reason about
- **▶** Performance issues:
  - Taking a decision may take an arbitrary number of steps (in adverse scenarios)
  - ► The leader is a **bottleneck** for all requests; even in leaderless approaches, **all nodes must process all operations in order**
  - ▶ Particularly sensitive to higher latency between nodes

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# Objective: the right level of consistency for Garage

<u>Constraints:</u> slow network (geographical distance), node unavailability/crashes Objective: maximize availability, maintain an *appropriate level of consistency* 

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#### 1. Weak consistency for most things

Example: PutObject

If two clients write the same object at the same time, one of the two is implicitly overwritten. No need to coordinate, use a *last-writer-wins register*.

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#### 2. Stronger consistency only when necessary

### Example: CreateBucket

A bucket is a reserved name in a shared namespace, two clients should be prevented from both creating the same bucket (*mutual exclusion*).

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### The possibility of *leaderless consensus*

Currently, Garage only has weak consistency. Is fast, but CreateBucket is broken!

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Leaderless consensus (Antoniadis et al., 2023) alleviates issues with RAFT and PAXOS:

- ▶ **No leader.** All nodes participate equally at each time step, and different nodes can be unavailable at different times without issues.
  - → better tolerance to the high latency (remove bottleneck issue)
  - $\rightarrow$  tolerates crash transparently
- ▶ **Simpler formalization.** The algorithm is very simple to express and to analyze in mathematical terms.

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One of the possible subjects for this PhD:

 $\rightarrow$  integration of leaderless consensus in Garage + testing + perf eval, etc.

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